

## **Robot Inserts for GRIPPEX® II**

## The Robot Inserts are suitable for all Gripping fingers used on Grippex II and IIS

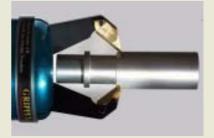




Gripping a big diameter



Gripping on a small surface



Deep Gripping



The inserts are made of middle hard steel. As option the inserts are available in others material as brass and plastic.

Order Code	Mounted on Fingers	Capacity D m m	Gripping-deep, L m m
GPX-II/RI-P	GPX-IIS/F52	4-48	20
	GPX-II/F60	4-55	20
	GPX-II/F80	4-75	20 (ø50 - ø75)*
			25 (ø30 - ø50)*
			30 (ø4 - ø30)*
	GPX-II/F105	4-100	20 (ø50 - ø100)*
			25 (ø25 - ø55)*
			38 (ø4 - ø25)*

\*) L - meausure in the diameter range

The design make it possible to grip on very small surface and also bridge untouchable surface.

A low-cost Robot Function is achieved when using Grippex II as a quick Pick-Up unit linked between a simple Loader/Unloader and the lathe's chuck. It may as well unload finished parts from a sub-spindle.

Gripping is achieved without any adjustment within whole gripping range. This makes it an easy task to grip raw material as well as finished parts using the same fingers set on Grippex II.